# Enriched graphs with applications to organic chemistry and trees 

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## Prelude (First of two unrelated questions)

Consider a type family $B$ over $A$. The $W$-type $\mathbb{W}(A, B)$ is inductively generated by one constructor

$$
\text { tree }: \prod_{(x: A)}(B(x) \rightarrow \mathbb{W}(A, B)) \rightarrow \mathbb{W}(A, B)
$$

## Question 1 (A question that shouldn't be asked)

Elements of W-types are often said to be trees. According to what concept of tree can we indeed view elements of W-types as trees?

## Goals

- Understand various concepts of trees and how they are related.
- Establish a precise way in which to view elements of W-types as trees, i.e., to establish an embedding

$$
\mathbb{W}(A, B) \hookrightarrow \text { Tree }
$$

for an appropriate notion of tree.

## Prelude (Second of two unrelated questions)

## Isomerism

There are molecules that have the same underlying graph, but nevertheless we can distinguish them based on their spatial arrangement. Such pairs of molecules are called isomers.

## Question 2

How do we define hydrocarbons in univalent mathematics in such a way that distinct isomers are correctly distinguished?


Image credit:
Ben Mills, Wikipedia (Public Domain)

## Overview

## Goals

- To show how to be very careful about how we define concepts in univalent mathematics.
- To demonstrate the usefulness of higher group theory.

■ To break symmetries and make sure our concepts have the correct notion of equality.

## Formalization

The material presented today has been formalized in the agda-unimath library:

- Graphs and enriched graphs can be found in the graph-theory folder.
- Trees and W-types can be found in the trees folder.
- The type of hydrocarbons can be found in the organic-chemistry folder.


## Overview

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- To show how to be very careful about how we define concepts in univalent mathematics.
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## Evil goals

My real goal is to convince you that trees should be allowed to have multiple edges between nodes.

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Basic information on the agda-unimath library
Purpose of the agda-unimath library

- The agda-unimath library aims to be a general purpose library of formalized mathematics from a univalent point of view.
- The agda-unimath library aims to be an informative resource for mathematicians.
- The agda-unimath library contains currently only constructive univalent mathematics, but we are also open to contributions of classical univalent mathematics.


## Where to find us

■ Repository: https://github.com/UniMath/agda-unimath

- Website: https://unimath.github.io/agda-unimath/
- Discord: Univalent Agda (Community with over 425 members, discussing four univalent agda libraries)

Contributions in any area of mathematics are welcome.

## Contributors

The agda-unimath library is the largest and fastest growing library in Agda, with over 180,000 lines of code over more than 1100 files, compiled into a markdown book of approximately 3500 pages.

28 people have contributed so far (Thank you all!!)

- Egbert Rijke (349,358 ++, 207,170 --)
- Fredrik Bakke (30,138 ++, 22,397 --)
- Éléonore Mangel (25,885 ++, 12,287 --)
- Elisabeth Bonnevier ( $10,220++, 7,258--)$

■ Jonathan Prieto-Cubides (107,296 ++, 101,727 --)

- Raymond Baker (2,250 ++, 1,005 --)
- Bryan Lu (4,479 ++, 2,494 --)
- Fernando Chu (6,856 ++, 912 --)
- Elif Uskuplu (1,384 ++, 747 --)
- Victor Blanchi (10,378 ++, 1,474 --)


## Contents of the agda-unimath library

Mathematical subjects in agda-unimath

- Category theory
- Commutative algebra
- Elementary number theory
- Finite group theory
- Foundation
- Graph theory
- Group theory
- Higher group theory
- Linear algebra
- Lists
- OEIS
- Order theory
- Organic chemistry
- Orth. factorization systems
- Polytopes
- Real numbers
- Ring theory
- Set theory
- Species
- Structured types
- Synthetic homotopy theory
- Trees
- Type theories
- Univalent combinatorics

■ Universal algebra

## Part I

## Undirected graphs and trees

## Traditional definitions of trees in graph theory

## Definition

A tree is an undirected graph $G$ satisfying any of the following equivalent conditions:

1. $G$ is connected and acyclic.
2. $G$ is acyclic, and a simple cycle is formed if any edge is added to $G$.
3. $G$ is connected, but would become disconnected if any single edge is removed from $G$.
4. Any two vertices are connected by a unique path (i.e., a walk that does not repeat vertices).

- We would like to give a positive definition of trees. The condition that a graph has no cycles is not positive. Removing an edge requires decidable equality on edges.
- The fourth definition is either negative or wrong. Any two vertices in the following graph are connected by a unique path:


## Unordered pairs of elements

## Definition

The type of unordered pairs of elements in a type $A$ is defined by

$$
\text { unordered-pair }(A):=\sum_{\left(I: B S_{2}\right)} A^{\prime} .
$$

## Equality of unordered pairs

For any two unordered pairs $(I, a)$ and $(J, b)$ of elements in $A$ we have

$$
((I, a)=(J, b)) \simeq \sum_{(e: I \simeq J)} a \sim b \circ e .
$$

## Standard unordered pairs

Given two elements $a, b: A$, the standard unordered pair $\{a, b\}$ is defined by

$$
\{a, b\}:=\left(\mathrm{Fin}_{2},(0 \mapsto a ; 1 \mapsto b)\right) .
$$

## Undirected graphs

## Definition

An (undirected) graph $G \doteq(V, E)$ consists of

- A type $V$ of vertices
- A type family

$$
E: \text { unordered-pair }(V) \rightarrow \mathcal{U}
$$

of half-edges, indexed by unordered pairs.

## Remark

- If $e: E(\{x, y\})$ is a half-edge, we think of it as the half-edge starting at $x$ pointing in the direction of $y$. We have $E(\{x, y\}) \simeq E(\{y, x\})$ which relates the two halves of an edge.
- Graphs can have multiple half-edges between vertices.
- Graphs can have loops (half-edges from a vertex pointing to itself).
- We don't make any restriction on the truncation levels of the vertices or the edges.

Two graphs with one vertex

## Example

Consider the graph with

$$
\begin{aligned}
V & :=\mathbf{1} \\
E(X, f) & :=\mathbf{1}
\end{aligned}
$$

Then $E(\{*, *\}):=\mathbf{1}$ so this graph has one half-edge. The total space of all edges is

$$
\sum_{(X, f)} E(X, f) \simeq B S_{2}
$$

There is indeed only half an edge! This graph looks like


## Example

Consider the graph with

$$
\begin{aligned}
V & :=\mathbf{1} \\
E(X, f) & :=X
\end{aligned}
$$

Then $E(\{*, *\}):=\operatorname{Fin}(2)$ so this graph has two half-edges. The total space of all edges is

$$
\sum_{(X, f)} E(X, f) \simeq \mathbf{1} .
$$

This graph has a loop on the unique vertex. This graph looks like

## Equivalences of undirected graphs

## Functoriality of unordered pairs

Given a map $f: A \rightarrow B$ we obtain a map

$$
\text { unordered-pair }(f) \text { : unordered-pair }(A) \rightarrow \text { unordered-pair }(B)
$$

given by unordered-pair $(f)(I, a):=(I, f \circ a)$. If $f$ is an equivalence, then so is unordered-pair $(f)$.

## Equivalences of undirected graphs

An equivalence of undirected graphs $G \simeq H$ consists of

- An equivalence $e_{V}: V_{G} \simeq V_{H}$.
- A family of equivalences

$$
e_{E}: \prod_{\left(p: \text { unordered-pair }\left(V_{G}\right)\right)} E_{G}(p) \simeq E_{H}\left(\text { unordered-pair }\left(e_{V}, p\right)\right) .
$$

By univalence it follows that $(G=H) \simeq(G \simeq H)$.

Walks in undirected graphs

## Idea

A walk from $a$ to $b$ in a graph $G$ is a sequence

$$
a=x_{0} \stackrel{e_{1}}{\int} x_{1} \stackrel{e_{2}}{x_{2}} x_{2} \stackrel{e_{3}}{x_{3}} \stackrel{e_{4}}{\cdots} \xlongequal{e_{n}} x_{n}=b .
$$

## Definition

Given a vertex $a$ of an undirected graph $G \doteq(V, E)$, the type family

$$
\text { walk(a) : V } \rightarrow \mathcal{U}
$$

of walks in $G$ starting at $a$ is defined inductively by

$$
\begin{aligned}
\text { refl }: & \text { walk }(a, a) \\
\text { cons }: & \prod_{((I, b): \text { unordered-pair }(V))} \prod_{(i: I)} E(I, b) \rightarrow \text { walk }\left(a, b_{i}\right) \rightarrow \text { walk }\left(a, b_{\sigma(i)}\right)
\end{aligned}
$$

where $\sigma: I \rightarrow I$ is the swap function.

The edges on a walk

## Definition

Consider an unordered pair $p$ of vertices and an edge $e: E(p)$ in a graph $G$. We define the type family

$$
\text { is-edge-on-walk }(e): \prod_{(b: V)} \text { walk }(a, b) \rightarrow \mathcal{U}
$$

by

$$
\text { is-edge-on-walk(e, refl) := } \varnothing \text {, }
$$

is-edge-on-walk $\left(e, \operatorname{cons}\left(p^{\prime}, i, e^{\prime}, w\right)\right):=\left((p, e)=\left(p^{\prime}, e^{\prime}\right)\right)+$ is-edge-on-walk $(e, w)$.
Then we define

$$
\text { edge-on-walk }(w):=\sum_{(p: u n o r d e r e d-p a i r(V))} \sum_{(e: E(p))} \text { is-edge-on-walk(e,w). }
$$

## Observation

One easily verifies that edge-on-walk $(w) \simeq \operatorname{Fin}_{n}$ where $n$ is the length of $w$.

## Undirected trees

## Definition

There is an obvious projection

$$
\pi_{w}: \text { edge-on-walk }(w) \rightarrow \sum_{(p: \text { unordered-pair }(V))} E(p) .
$$

We say that the walk $w$ is a trail if $\pi_{w}$ is injective.

## Observation

- Being a trail is a proposition, because edge-on-walk $(w)$ is a standard finite type, and hence a set.
- Why don't we ask that $\pi_{w}$ is an embedding?


## Definition

An undirected tree is an undirected graph $T$ such that for every two vertices a and $b$ in $T$ the type

$$
\operatorname{trail}(a, b)
$$

of trails from $a$ to $b$ is contractible.

A very unfortunate theorem

## Theorem ( $R$ )

The type of nodes (i.e. vertices) of an undirected tree has decidable equality.

## Proof.

Consider two nodes $a$ and $b$ in $T$.

1. One routinely verifies that the type $a=b$ is equivalent to the type of walks of length 0 from $a$ to $b$.
2. Furthermore, every walk of length 0 is a trail since the type of edges on such walks is empty.
3. Then $a=b$ if and only if the unique trail from $a$ to $b$ has length 0 , which is decidable.

## Symmetric identity types

## Definition

The symmetric identity type on a type $A$ is the type family $\widetilde{l d}:$ unordered-pair $(A) \rightarrow \mathcal{U}$ defined by

$$
\tilde{I d}(I, a):=\sum_{(x: A)} \prod_{(i: I)} x=a_{i}
$$

## Proposition

The symmetric identity type equips the identity type with a fully coherent $\mathbb{Z} / 2$-action in the sense that the following diagram commutes


## Acyclic undirected graphs

## Definition

A geometric realization of an undirected graph $G \doteq(V, E)$ is a homotopy initial type $X$ equipped with

$$
\begin{aligned}
& i: V \rightarrow X \\
& p: \prod_{(I, x): \text { unordered-pair }(V)} E(I, x) \rightarrow \widetilde{I d}(I, x)
\end{aligned}
$$

## Definition

An acyclic undirected graph is an undirected graph of which the geometric realization is contractible.

## Example

Since there are nontrivial acyclic types, there are nontrivial acyclic undirected graphs which are not trees in the previous sense.

Half-time recap

## Elements of W-types as trees?

Suddenly our quest of figuring out in what sense elements of W-types are trees looks rather impossible.

- The trees we defined above in the graph theoretical sense must have decidable equality. In particular they are sets.
- W-types can have arbitrarily high truncation levels, so we don't expect their elements to be set-level objects.


## Conclusions

- We don't expect elements of W-types to be trees in the above sense.
- Let's try our luck with organic chemistry.


## Part II

## Enriched graphs and univalent hydrocarbons

The basic idea in the definition of the hydrocarbons

## Main points

- A hydrocarbon consists of hydrogen atoms and carbon atoms.
- Hydrogen atoms form exactly one bond.
- Carbon atoms form exactly four bonds.
- To account for the spatial arrangement of a hydrocarbon, we must restrict the symmetry group of each carbon atom:
- Any symmetry that fixes one point, must preserve the cyclic ordering of the remaining three points.
- Any symmetry that fixes two points also fixes the remaining two points.


Image credit:
Ben Mills, Wikipedia (Public Domain)

In other words, the symmetry group of a carbon atom in 3-space is $A_{4}$.

## Higher groups

## Definition

A higher group $G$ consists of a pointed connected type $B G$.

- The type $B G$ is called the delooping of $G$.
- The base point of $B G$ is called the shape of $G$.
- The underlying type of $G$ is defined to be $\Omega B G$. We often write $G$ for $\Omega B G$.


## Definition

A $G$-action on a type $X$ consists of a type family $Y: B G \rightarrow \mathcal{U}$ equipped with an equivalence $e: X \simeq Y(*)$. Given such a $G$-action on $X$, we define the action $\mu$ of $G$ on $X$ such that $\mu(\mathrm{g}): X \rightarrow X$ is the unique map equipped with a homotopy

## Enriched undirected graphs

## Definition

Consider an undirected graph $G \doteq(V, E)$, and let $v: V$. Then we define the neighborhood of $v$ by

$$
\operatorname{Neighborhood~}_{G}(v):=\sum_{(x: V)} E(\{v, x\})
$$

## Definition

Consider a type $A$ and a type family $B$ over $A$. An ( $A, B$ )-enriched undirected graph consists of

- An undirected graph $G \doteq(V, E)$.
- A map sh: $V \rightarrow A$. We call $\operatorname{sh}(v)$ the shape of $v$.
- For each vertex $v: V$ an equivalence

$$
e_{v}: B(\operatorname{sh}(v)) \simeq \text { Neighborhood }_{G}(v) .
$$

## $\infty$-group actions of $(A, B)$-enriched graphs

## Remark

Consider an $(A, B)$-enriched graph ( $V, E$, sh, $e$ ).

- For every vertex $v: V$ we obtain an $\infty$-group

$$
B G_{v}:=\sum_{(x: A)}\|\operatorname{sh}(v)=x\|
$$

Its base point is $\operatorname{sh}(v)$, and we write $G_{v}$ for its underlying type. $G_{v}$ is called the symmetry group of $v$.

- For every vertex $v: V$ we obtain a $G_{v}$-type

$$
B: B G(v) \rightarrow \mathcal{U}
$$

given by restricting $B$.

- By the equivalence $B(\operatorname{sh}(v)) \simeq$ Neighborhood $(v)$ we obtain an action

$$
G_{v} \rightarrow(\operatorname{Neighborhood}(v) \rightarrow \text { Neighborhood }(v))
$$

of the symmetry group of $v$ on its neighborhood.

## Equivalences of $(A, B)$-enriched graphs

## Definition

An equivalence between two ( $A, B$ )-enriched graphs ( $V, E$, sh, $e$ ) and ( $V^{\prime}, E^{\prime}$, sh', $e^{\prime}$ ) consists of

- An equivalence $\alpha: V \simeq V^{\prime}$
- A family of equivalences $\beta: E(p) \simeq E^{\prime}$ (unordered-pair $(\alpha, p)$ ) for each $p$ : unordered-pair( $V$ )
- A homotopy $\gamma:$ sh $\sim s h^{\prime} \circ \alpha$
- For each vertex $v$ a commuting square

$$
\begin{array}{lr}
B(\operatorname{sh}(v)) \longrightarrow & \operatorname{tr}_{B}(\gamma(v)) \\
e(v) \downarrow & B\left(\operatorname{sh}^{\prime}(\alpha(v))\right) \\
\downarrow e(\alpha(v))
\end{array}
$$

$\operatorname{Neighborhood~}_{(V, E)}(v) \xrightarrow[\operatorname{Neighborhood~}_{(\alpha, \beta)}(v)]{ }$ Neighborhood $_{\left(V^{\prime}, E^{\prime}\right)}(\alpha(v))$

## Remark

Equivalences of $(A, B)$-enriched graphs are shape-preserving equivalences of graphs that also preserve the action of the symmetry group of a vertex on its

## Broken symmetries

## Theorem

Given two $(A, B)$-enriched graphs ( $V, E$, sh, $e$ ) and $\left(V^{\prime}, E^{\prime}, s h^{\prime}, e^{\prime}\right)$, we have an equivalence

$$
\left((V, E, \operatorname{sh}, e)=\left(V^{\prime}, E^{\prime}, \operatorname{sh}, e^{\prime}\right)\right) \simeq\left((V, E, \operatorname{sh}, e) \simeq\left(V^{\prime}, E^{\prime}, \operatorname{sh}^{\prime}, e^{\prime}\right)\right) .
$$

The sign homomorphism
Theorem (Mangel, R.)
For any $n: \mathbb{N}$ there is a map $\sigma: B S_{n} \rightarrow B S_{2}$ such that the square of group homomorphisms

$$
\begin{aligned}
& S_{n} \xrightarrow{\text { sign }} S_{2} \\
& \cong \downarrow \cong \\
& \Omega B S_{n} \xrightarrow[\Omega \sigma]{ } \Omega B S_{2}
\end{aligned}
$$

commutes.

## Remark

The construction of $\sigma$ involves:

- A functorial construction that turns an arbitrary $n$-element set $X$ into a 2-element set $\sigma(X)$.
- As a functor, $\sigma: B S_{n} \rightarrow B S_{2}$ must be full (surjective on morphisms).
- In HoTT we say that $\sigma$ must be 0-connected.


## The alternating groups

## Definition

We define $B A_{n}$ as the pullback

$$
\begin{gathered}
B A_{n} \longrightarrow \\
\downarrow \\
B S_{n} \longrightarrow \\
\\
\hline
\end{gathered}
$$

## Definition

- Define the type of hydrogen atoms to be

$$
\mathcal{H}:=\mathbf{1} .
$$

Note that there is a canonical map

$$
\gamma_{\mathcal{H}}: \mathcal{H} \rightarrow B S_{1} .
$$

- Define the type of carbon atoms to be

$$
\mathcal{C}:=B A_{4}
$$

where $B A_{4}$ is the classifying type of the alternating group $A_{4}$. Note that there is a canonical map

$$
\gamma_{\mathcal{C}}: \mathcal{C} \rightarrow B S_{4} .
$$

## Definition

The type of hydrocarbons is defined to be the type of $(A, B)$-enriched graphs where

$$
\begin{array}{ll}
A:=\mathcal{H}+\mathcal{C} & : \mathcal{U} \\
B:=\left[\gamma_{\mathcal{H}}, \gamma_{\mathcal{C}}\right] & : A \rightarrow \mathcal{U}
\end{array}
$$

such that

- The type of vertices is finite.
- The underlying graph is connected.
- The underlying graph has no loops.


## Part III

## Elements of W-types as enriched directed trees

## Elements of W-types as graphs

## Definition

Consider a $\mathbb{W}$-type $\mathbb{W}(A, B)$. We define a relation $\in: \mathbb{W}(A, B) \rightarrow \mathbb{W}(A, B) \rightarrow \mathcal{U}$ inductively by

$$
(x \in \operatorname{tree}(a, \alpha)):=\sum_{(b: B(a))} \alpha(b)=x .
$$

## Definition

Consider a $\mathbb{W}$-type $\mathbb{W}(A, B)$. We define node : $\mathbb{W}(A, B) \rightarrow \mathcal{U}$ inductively by

$$
\begin{aligned}
& r: \prod_{(w: \mathbb{W}(A, B))} \operatorname{node}(w) \\
& i: \prod_{(u, w: \mathbb{W}(A, B))} u \in w \rightarrow \operatorname{node}(u) \rightarrow \operatorname{node}(w) .
\end{aligned}
$$

and define edge : $\prod_{(w: W(A, B))} \operatorname{node}(w) \rightarrow \operatorname{node}(w) \rightarrow \mathcal{U}$ by

$$
\begin{aligned}
& r: \prod_{u, w: \mathbb{W}(A, B)} u \in w \rightarrow \operatorname{edge}(w, i(r(u)), r(w)) \\
& i: \prod_{u, w: W(A, B)} \prod_{(H: u \in w)} \prod_{(x, y: \operatorname{node}(u))} \operatorname{edge}(u, x, y) \rightarrow \operatorname{edge}(w, i(x), i(y)) .
\end{aligned}
$$

## Directed trees

## Definition

A directed graph $G \doteq(V, E)$ consists of a type $V$ of vertices and a binary type-valued relation $E: V \rightarrow V \rightarrow \mathcal{U}$ of edges. Walks in directed graphs are defined analogously to the undirected case.

## Definition

Consider a directed graph $G \doteq(V, E)$ equipped with a distinguised vertex $r: V$. We say that $G$ is a directed tree if the type

$$
\text { walk }(x, r)
$$

of walks from $x$ to $r$ is contractible for every $x: V$. The vertices of a tree are called nodes and the distinguished node $r$ is called the root.

## Example

For each element $w: \mathbb{W}(A, B)$, the directed graph $G_{w}:=(\operatorname{node}(w)$, edge $(w))$ is a directed tree.

## Equivalent definitions of directed trees

## Proposition

Consider a directed graph $G=(V, E)$ equipped with a distinguished vertex $r$. The following conditions are equivalent:

1. The graph $G$ is a tree with root $r$.
2. For every vertex $x$ there is a walk from $x$ to $r$, and furthermore the type

$$
(r=x)+\sum_{(y: V)} E(x, y)
$$

is contractible.

## Theorem

The type of directed trees is equivalent to the type of infinite sequences

where $A_{0}$ is contractible. In particular, the type of nodes of a directed tree does not have to be a set.

## Comparison between directed and undirected trees

- The root in a directed tree is always an isolated point. Indeed, being the root is decidable by checking that the unique trail to the root has length 0 .
- In a directed tree, the type

$$
\sum_{(y: V)} E(x, y)
$$

is contractible for every $x \neq r$, while $E(x, y)$ itself needs not be subterminal.

- In an undirected tree there is at most one edge on every unordered pair $\{x, y\}$ of nodes.
- Every undirected rooted tree is a directed rooted tree in a canonical way. The edges can be directed towards the root.
- Nevertheless, the undirected tree condition is much stronger than the directed tree condition, since it asks for a unique undirected trail between every two nodes, while the directed tree condition only asks for a unique trail from every node to the root.
- Elements of W-types are directed trees. However, they have a bit more structure!


## Enriched directed trees

## Definition

An $(A, B)$-enriched directed tree consists of

- A directed tree $T \doteq(N, E)$.
- A map sh : $N \rightarrow A$. The value $\operatorname{sh}(x)$ is said to be the shape of the node $x$.
- For each node $x: N$ an equivalence

$$
B(\operatorname{sh}(x)) \simeq \sum_{(y: N)} E(y, x)
$$

## Equality of enriched directed trees

Elements of $W$-types as enriched directed trees
The underlying tree of an element $w: W(A, B)$ has the structure of an $(A, B)$-enriched directed tree:

- We define $\operatorname{sh}(w)$ recursively by

$$
\begin{aligned}
\operatorname{sh}(\operatorname{tree}(a, \alpha))(r(w)) & :=a \\
\operatorname{sh}(\operatorname{tree}(a, \alpha))(i(x)) & :=\operatorname{sh}(\alpha(b), x)
\end{aligned}
$$

for any $b: B(a)$ and $x: \operatorname{node}(\alpha(b))$.

- We define $B(\operatorname{sh}(w, x)) \simeq \sum_{(y: \operatorname{node}(w))}$ edge $(w, y, x)$ recursively by

$$
\begin{aligned}
B(a) & \simeq \sum_{u: \mathbb{W}(A, B)} u \in w \\
& \simeq \sum_{u: \mathbb{W}(A, B)} \sum_{H: u \in w} \sum_{y: \operatorname{node}(u)} \operatorname{edge}(w, i(y), r(w)) \\
& \simeq \sum_{(y: \operatorname{node}(w))} \operatorname{edge}(w, y, r(w)) .
\end{aligned}
$$

The recursive step is handled similarly.

## Elements of W-types are enriched directed trees

## Goal

There is an embedding

$$
\mathbb{W}(A, B) \hookrightarrow(A, B) \text {-Enriched-Directed-Tree }
$$

- This requires us to match the identity type of W-types with equivalences of enriched directed trees

■ I thought it would be formalizable in a week or two. Alas, it wasn't! Due to the homotopical nature of enriched directed trees it is not possible to pattern match your way out.

- I am now developing a lot of theory of (enriched) directed trees in agda-unimath in a draft PR of $\sim 5000$ LOC.
- Even though I have an informal argument to believe that this is true, I'm not calling the above goal a theorem until it is formalized. Too much work in homotopy type theory, including my own, hasn't been formalized and contains inaccuracies!

Oriented rooted binary trees

## Definition

An oriented binary tree is a directed tree $T \doteq(N, E)$ equipped with a map

$$
\text { sh: } N \rightarrow \mathrm{Fin}_{2}
$$

and two families of equivalences:

- For every node $x: N$ such that $\operatorname{sh}(x)=0$ an equivalence

$$
\varnothing \simeq \sum_{(y: N)} E(y, x) .
$$

- For every node $x$ : $N$ such that $\operatorname{sh}(x)=1$ an equivalence $\mathrm{Fin}_{2} \simeq \sum_{(y: N)} E(y, x)$.
In other words, oriented binary trees are $(A, B)$-enriched directed trees where $A:=\mathrm{Fin}_{2}$, and $B(0):=\varnothing$, and $B(1):=\mathrm{Fin}_{2}$.


## Consequence of $\mathbb{W}(A, B) \hookrightarrow(A, B)$-Enriched-Directed-Tree

The type $\mathbb{W}\left(\mathrm{Fin}_{2},\left(0 \mapsto \varnothing ; 1 \mapsto \mathrm{Fin}_{2}\right)\right)$ is equivalent to the finite oriented binary trees.

## Binary trees

## Definition

A binary tree is a directed tree $T \doteq(N, E)$ equipped with a map

$$
\text { sh }: N \rightarrow \sum_{(X: U)}\left\|\mathrm{Fin}_{0} \simeq X\right\| \vee\left\|\mathrm{Fin}_{2} \simeq X\right\|
$$

and for every node $x: N$ an equivalence

$$
\operatorname{sh}(x) \simeq \sum_{(y: N)} E(y, x) .
$$

In other words, binary trees are $(A, B)$-enriched directed trees where $A$ is the type of shapes defined above, and $B(X):=X$.

## Consequence of $\mathbb{W}(A, B) \hookrightarrow(A, B)$-Enriched-Directed-Tree

The type $\mathbb{W}\left(\sum_{(X: \mathcal{U})}\left\|\mathrm{Fin}_{0} \simeq X\right\| \vee\left\|\mathrm{Fin}_{2} \simeq X\right\|, X \mapsto X\right)$ is equivalent to the finite binary trees.

Note that being a binary tree is a property, while being an oriented binary tree is structure.

## Oriented finitely branching trees

## Definition

An oriented finitely branching tree is a directed tree $T \doteq(N, E)$ equipped with a map

$$
\text { sh : } N \rightarrow \mathbb{N}
$$

and for every node $x: N$ an equivalence

$$
\operatorname{Fin}_{\operatorname{sh}(x)} \simeq \sum_{(y: N)} E(y, x) .
$$

In other words, oriented finitely branching trees are $(A, B)$-enriched directed trees where $A:=\mathbb{N}$, and $B(n):=\mathrm{Fin}_{n}$.

## Consequence of $\mathbb{W}(A, B) \hookrightarrow(A, B)$-Enriched-Directed-Tree

The type $\mathbb{W}(\mathbb{N}$, Fin $)$ is equivalent to the finite oriented finitely branching trees.

## Finitely branching trees

## Definition

A finitely branching tree is a directed tree $T \doteq(N, E)$ equipped with a map

$$
\text { sh: } N \rightarrow \mathbb{F}
$$

and for every node $x: N$ an equivalence

$$
\operatorname{sh}(x) \simeq \sum_{(y: N)} E(y, x)
$$

In other words, finitely branching trees are $(A, B)$-enriched directed trees where $A:=\mathbb{F}$, and $B(X):=X$.

Consequence of $\mathbb{W}(A, B) \hookrightarrow(A, B)$-Enriched-Directed-Tree
The type $\mathbb{W}(\mathbb{F}, X \mapsto X)$ is equivalent to the type of finite trees.

Note again that being a finitely branching tree is a property, while being an oriented finitely branching tree is structure.

## Conclusion

## Closing remarks

Enrichment does not break symmetries if and only if $B$ is a univalent type family over $A$. Indeed, in this case the enrichment data is a proposition. In particular, if $\mathbb{W}(A, B)$ is an extensional $\mathbb{W}$-type in the sense of Gylterud, then $\mathbb{W}(A, B)$ is the type of all well-founded directed trees with branching in the subuniverse $A \hookrightarrow \mathcal{U}$.

Thank you for your attention!

